UNIVERSITY OF BOLTON SCHOOL OF ENGINEERING BEng (Hons) MECHANICAL ENGINEERING SEMESTER ONE EXAMINATIONS 2019/20 ENGINEERING PRINCIPLES 1 MODULE NO: AME4062

1.

Date: Tuesday 14th January 2020

Time: 10:00 – 12:00

INSTRUCTIONS TO CANDIDATES:

There are <u>SIX</u> questions.

- 2. Answer <u>TWO</u> questions from each of the sections A and B.
- 3. Use a separate answer book for sections A and B.
- Maximum marks for each part/question are shown in brackets. Each question is worth 25 marks.
- 4. Formula sheets (attached)

<u>Section A</u> - Answer any <u>TWO</u> questions from this section.

1. (a) Find a vector joining the points (1,3,2) and (2,5,6). (2 marks) The vectors $\mathbf{a} = \mathbf{i} + 3\mathbf{j} + 2\mathbf{k}$ and $\mathbf{b} = 2\mathbf{i} + 5\mathbf{j} + 6\mathbf{k}$. Find the (b) magnitudes of the vectors a and b. (4 marks) (c) Evaluate $\boldsymbol{a} \cdot \boldsymbol{b}$. (2 marks) Find the angle between the vectors **a** and **b**. (d) (4 marks) (e) Find a vector which is perpendicular to both vectors **a** and **b**. (4 marks) Calculate the work done by a constant force *F* of 12*N* whose line (f) of action is parallel to 2i + 3j - 2k when it moves a bead a distance of 4*m* along a straight wire which is in the direction of the vector -2i + j - 3k. (9 marks)

Total 25 marks

2. (a) Simplify the fraction

 $\frac{\sin^3\theta + \sin\theta\cos^2\theta}{\cos\theta}$

(4 marks)

(b) Solve the equation

$$1 + \sin\theta \cos^2\theta = \sin\theta$$

for $0^{\circ} \leq \theta \leq 180^{\circ}$.

(6 marks)

(c) Find all solutions of the equation

$$sin2\theta = sin\theta$$

for
$$0^{\circ} \leq \theta \leq 360^{\circ}$$
.

(7 marks)

(d) If $3sin\theta + 4cos\theta$ is written in the form $rsin(\theta + \alpha)$, show how to find the value of *r* and α .

(5 marks)

Find the greatest and least value of

 $12sin\theta + 16cos\theta$.

(3 marks)

Total 25 marks

3. (a) Simplify

ln√3

(3 marks)

(5 marks)

(b) Solve the equation

$$4^{x+2} = 3^{x-1}$$

leaving your answer in terms of natural logarithms and in its simplest form.

(c) Solve the equation

$$4^{6x} - 4^{3x+1} - 5 = 0$$

leaving your answer in terms of natural logarithms and in its simplest form.

(5 marks)

(d) Use the inverse matrix method to solve the two-by-two system of linear equations

$$3x + 2y = -2$$
$$x + 4y = 6.$$

(5 marks)

(e) If $i^2 = -1$, show that

$$\left(\frac{1+i}{1-i}\right)^2$$

takes the same value.

(2 marks)

Show also that i^i is real.

(5 marks)

Total 25 marks

END OF SECTION A

<u>Section B</u> - Answer <u>ANY TWO</u> questions from this section.

- 4. Two forces are applied to the bracket BCD as shown in Fig. Q4.
 - (a) Knowing that the control rod AB is to be made of a steel having an ultimate normal stress of 500 MPa, determine the diameter of the rod for which the factor of safety with respect to failure will be 3.

(10 marks)

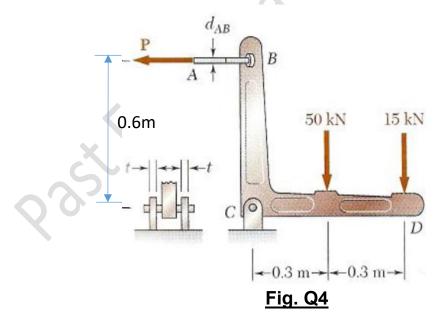
(b) The pin at C is to be made of a steel having an ultimate shearing stress of 350 MPa, Determine the diameter of the pin C for which the factor of safety with respect to shear will be 3.5

(8 marks)

(c) Determine the required thickness of the bracket supports at C knowing that the allowable bearing stress of the steel used is 300 MPa.

(7 marks)

Total 25 marks



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5. A simply supported beam carries two concentrated lateral loads and a uniformly distributed load over its entire length as shown in **Fig.Q5**. Determine:

(a) Reaction forces, R1 & R2, at the supports(5 marks)(b) Construct the shear force diagram for the beam(8 marks)(c) Construct the bending moment diagram for the beam(8 marks)(d) Find the position of maximum bending moment(4 marks)

Total 25 marks

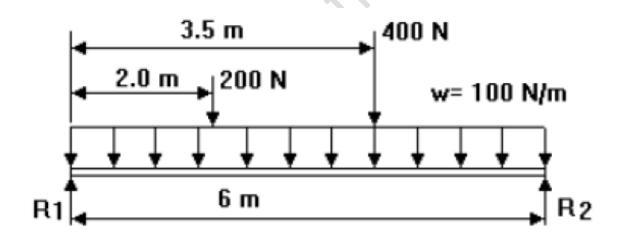


Fig.Q5

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6. (a) Define the term torque load & its impact on bodies and mention three examples of its applications in engineering.

(5 marks)

- (b) A stepped shaft has the appearance shown in <u>Fig.Q6</u>. The region *AB* is aluminium, having G = 28 GPa, and the region *BC* is steel, having G = 84 GPa. The aluminium portion is of solid circular cross section 45 mm in diameter, and the steel region is circular with 60-mm outside diameter and 30-mm inside diameter. A torsional load of 4000 N \cdot m is applied at point B, whereas ends *A* and *C* are rigidly clamped. Determine the followings:
 - (i) The maximum shearing stress in each material

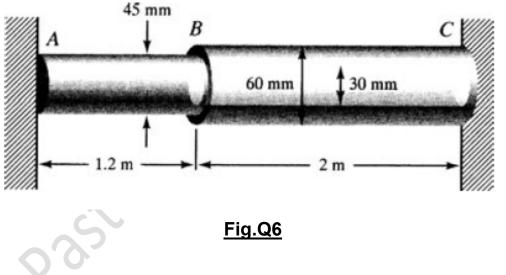
The angle of twist at B.

(ii)

(15 marks)

(5 marks)

Total 25 marks



END OF QUESTIONS

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$a^m \cdot a^n$	a^{m+n}
$\frac{a^m}{a^n}$	a^{m-n}
$(a^m)^n$	a^{mn}
$\frac{1}{a^m}$	a^{-m}
$a^{\frac{1}{m}}$	$\sqrt[m]{a}$
a^0	1

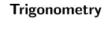
Quadratic equations

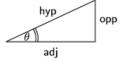
The equation:

$$ax^2 + bx + c = 0$$

has solutions:

$$x \;=\; \frac{-b\pm\sqrt{b^2-4ac}}{2a}$$



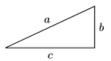


$\sin(\theta)$	=	opp hyp
$\cos(\theta)$	=	adj hyp
$\tan(\theta)$	=	opp adj

Laws of Logarithms

$\boxed{\log_a(b) + \log_a(c)}$	$\log_a(bc)$
$\log_a(b) - \log_a(c)$	$\log_a\left(\frac{b}{c}\right)$
$\log_a(b^c)$	$c \log_a(b)$
$\log_a(1)$	0
$\log_a(a)$	1

Pythagoras' theorem



$$a^2 = b^2 + c^2$$

Trigonometric Identities

$$\sin^2(\theta) + \cos^2(\theta) = 1$$

$$\sin(A+B) = \sin(A)\cos(B) + \cos(A)\sin(B)$$

$$\cos(A+B) = \cos(A)\cos(B) - \sin(A)\sin(B)$$

$$\sin(2A) = 2\cos(A)\sin(A)$$

$$\cos(2A) = \cos^2(A) - \sin^2(A)$$
$$= 2\cos^2 A - 1$$
$$= 1 - 2\sin^2 A$$

Vectors

Dot or scalar product

If $a = a_1 i + a_2 j + a_3 k$ and $b = b_1 i + b_2 j + b_3 k$, then $a \cdot b = a_1 b_1 + a_2 b_2 + a_3 b_3$

If θ is the angle between the vectors **a** and **b**, and $a = (a_1^2 + a_2^2 + a_3^2)^{1/2}$, the magnitude of **a**, and similarly for the vector **b**, then $\mathbf{a} \cdot \mathbf{b} = abcos\theta$.

If $\mathbf{a} = a_1\mathbf{i} + a_2\mathbf{j} + a_3\mathbf{k}$ and $\mathbf{b} = b_1\mathbf{i} + b_2\mathbf{j} + b_3\mathbf{k}$, then $\mathbf{a} \wedge \mathbf{b} = \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_2 \end{vmatrix}$

Also, $a \wedge b = absin\theta n$, n being a unit vector perpendicular to a and b such that $(a, b, a \wedge b)$ form a right-handed set.

Matrices

If
$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
, then $A^{-1} = \frac{1}{detA} \begin{pmatrix} d & -b \\ -c & a \end{pmatrix}$ where $detA = ad - bc$.

Complex Numbers

De Moivre's Theorem

$$(\cos\theta + i\sin\theta)^n = \cos(n\theta) + i\sin(n\theta)$$

Exponential form

$$e^{\pm i\theta} = \cos\theta \pm i\sin\theta$$

Mechanics

Notation:

σ - normal stress (Pa)	v - Poisson's ratio
τ- shear stress (Pa)	α - coefficient of thermal expansion
ε - normal strain (m/m)	(/°C)
γ - shearing strain (m/m)	M - bending moment in beams
I - area moment of inertia (m ⁴)	T - torque in shafts
J - polar area moment	ΔT - temperature change (EC)
of inertia (m ⁴)	F.S factor of safety = <u>Ultimate stress</u>
E - modulus of elasticity (Pa)	Allowable stress
G - modulus of rigidity (Pa)	$\varepsilon_t = \alpha \Delta T$ - thermal strain

Normal Stress and Strain:

If the line of action of the load, P, passes through the centroid of the resisting cross-section:

axial stress =
$$\sigma = \frac{P}{A}$$

axial strain = $\varepsilon = \frac{\delta}{L}$

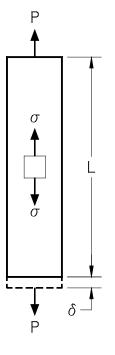
If the material is also linear, then:

Uniaxial Hooke's Law:
$$\varepsilon = \frac{\sigma}{E}$$

where, E is the modulus of elasticity for the material

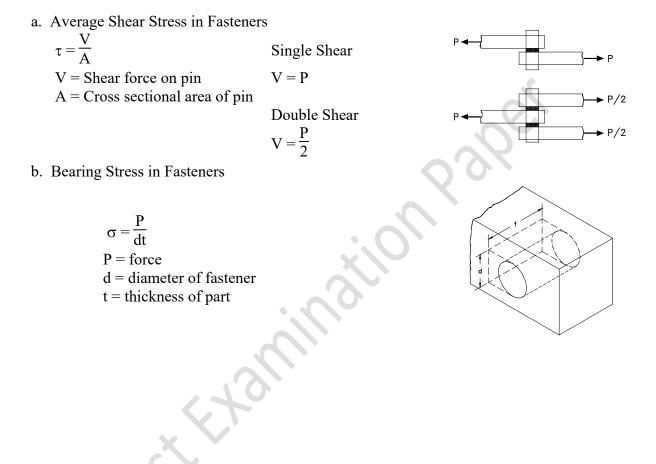
The relationship between axial loading and deformation becomes

axial deformation:
$$\delta = \frac{PL}{AE}$$



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Shear Stress in Fasteners & Brackets:



Torsion of Circular Sections:

a. Shear stress

If the shaft has a circular cross section and the material remains in the linear-elastic region, the shear stress in the shaft varies as a linear function of the distance (ρ) from the center of the shaft and is given by:

shear stress :
$$\tau = \frac{T\rho}{J}$$

The maximum shear stress in the shaft is on the outer surface independent of whether the shaft is solid or hollow and is given by:

max shear stress :
$$\tau_{max} =$$

b. The polar area moment of inertia is:

solid section:
$$J = \frac{\pi r_o^4}{2}$$

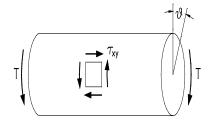
hollow section: $J = \frac{\pi}{2} (r_o^4 - r_i^4)$

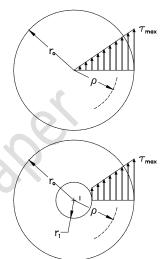
c. The calculated stresses act on the element as shown.

The deformation is measured by the angle of twist (θ) of one end relative to the other and is given by:

angle of twist :
$$\theta = \frac{TL}{JG}$$

where, G is the modulus of rigidity for the material and L is the length of shaft





END OF PAPER

theman