## UNIVERSITY OF BOLTON

## SCHOOL OF ENGINEERING

## BENG (HONS) IN MECHANICAL ENGINEERING

## SEMESTER TWO EXAMINATION 2018/2019

## ENGINEERING PRINCIPLES 2

## MODULE NO: AME4063 \& AME4053

Date: Wednesday 22 ${ }^{\text {nd }}$ May 2019
Time: 10:00-12:00

INSTRUCTIONS TO CANDIDATES:

This paper is split into two parts; Part A and Part B. There are THREE questions in Part A and THREE questions in Part B.

Answer FOUR questions in total; TWO questions from Part $A$ and TWO questions from Part B.

All questions carry equal marks.
Marks for parts of questions are shown in brackets.

This examination paper carries a total of 100 marks.

CANDIDATES REQUIRE:

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## Part A

Q1
a) A flywheel 0.9 m diameter has its initial angular velocity of $6 \mathrm{rad} / \mathrm{s}$ increased to its final angular velocity with an angular acceleration of $12 \mathrm{rad} / \mathrm{s}^{2}$ whilst making 100 revolutions.

Calculate:
i) The final angular velocity of the flywheel
ii) The time taken for the 100 revolutions
iii) The linear acceleration and final linear velocity of a point on the rim of the flywheel
b) A turbine rotor has a moment of inertia of $1.4 \mathrm{Mgm}^{2}$. Determine the acceleration torque required to accelerate the rotor from $26000 \mathrm{rev} / \mathrm{min}$ to $2700 \mathrm{rev} / \mathrm{min}$ in a time of 2 s . .
(10 marks)

## Total 25 marks

Q2
a) for the beam cross section shown in Figure Q2a find the centroid.


Figure Q2A

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## Q2 continued...

b) Define the moment of inertia and radius of gyration
(10 marks)

## Total 25 marks

Q3
a) Find the second moment of area and radius of gyration about the axis XX for the beam section shown in Figure Q3a.


Figure Q3a
b) A rectangular section beam has a depth of 100 mm and width 24 mm and is subject to a bending moment of 2.5 kN m. Calculate the maximum stress in the beam .Take $\mathrm{E}=206 \mathrm{GPa}$
C) A solid steel shaft 2 m long and 60 mm diameter rotates at $200 \mathrm{rev} / \mathrm{min}$. Calculate the torque when the maximum shear stress in the shaft is 70 MPa .

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## PART B

Q4) a) Calculate the derivative of the function $f$ defined by:

$$
f(x)=x^{2}
$$

from first principles.
(3 marks)
b) Calculate the first derivative of the following functions:
i) $\quad 5 e^{-2 x}+4 x^{3}$
ii) $\quad 2 \cos (3 x+6)$
(3 marks)
iii) $\quad 6 x e^{-4 x}$
iv) $\frac{2 x+1}{x^{2}+2}$
(3 marks)
c) Find and classify the stationary points of the curve $y=f(x)$ where the function $f$ is defined by:

$$
\begin{equation*}
f(x)=2 x^{3}-21 x^{2}+60 x+4 \tag{4marks}
\end{equation*}
$$

d) Consider the following equation:

$$
\mathrm{e}^{2 x}-8 x^{2}=4
$$

(i) Show there is a solution to this equation on the interval[0,2].
(ii) Use the method of bisection once to find a first approximation to the solution of the equation.
(iii) Using the approximation calculated in (ii) as your initial value, use the Newton-Raphson method to find a solution to the equation accurate to 2 decimal places.

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Q5) a) Evaluate the following definite integrals:
(i) $\int_{1}^{2}\left(10 x^{4}+\frac{1}{2} x^{2}\right) d x$
(ii) $\int_{0}^{\pi} x \cos (3 x) d x$
(iii) $\int_{0}^{2} \cos (2 x-4) d x$
using the substitution $u=g(x)=2 x-4$.
b) Find the area between the curves $y=2, y=\sqrt{x}$ and the $y$-axis, as indicated by the blue region in the following diagram:

c) Consider the following integral: $\quad \int_{0}^{3} \frac{1}{x^{3}+10} d x$.

Approximate the value of this integral with 6 strips using:
(i) the trapezoidal rule; and
(ii) Simpson's rule.

Give your answers to 4 decimal places.

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Q6) a) Find the particular solution to the following differential equations:
(i) $\left\{\begin{array}{l}y^{\prime}=2 x y \\ y(0)=4\end{array}\right.$
(5 marks)
(ii) $\left\{\begin{array}{c}x y^{\prime}+3 y=4 x \\ y(2)=3\end{array}\right.$
(5 marks)
(iii) $\left\{\begin{array}{c}y^{\prime}+x=\cos (2 x) \\ y(0)=1\end{array}\right.$.
b) Find the particular solution of the differential equation:

$$
\left\{\begin{array}{c}
y^{\prime \prime}+7 y^{\prime}+12 y=0  \tag{10marks}\\
y(0)=1 \\
y^{\prime}(0)=1
\end{array}\right.
$$

Total: 25 marks

## END OF PART B

END OF QUESTIONS

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## Formula Sheet

$\underline{2^{\text {nd }} \text { Moments of Area }}$
Rectangle $\quad I=\frac{\mathrm{bd}^{3}}{12}$
Circle $\quad \mathrm{I}=\frac{\pi d^{4}}{64}$
Polar $\mathrm{J}=\frac{\pi d^{4}}{32}$
Parallel Axis Theorem
$I_{x x}=I_{G G}+A h^{2}$
Bending
$\frac{M}{l}=\frac{\sigma}{y}=\frac{E}{R}$

## Torsion

$\frac{T}{J}=\frac{\tau}{r}=\frac{G \vartheta}{\ell}$
Motion
$v=u+a t$
$\omega_{2}=\omega_{1}+\alpha t$
$v^{2}=u^{2}+2 a s$ $\omega_{2}^{2}=\omega_{1}^{2}+2 \alpha \vartheta$
$\mathrm{s}=\left(\frac{u+v}{2}\right) t$
$\vartheta=\left(\frac{\omega_{1}+\omega_{2}}{2}\right) t$
$s=u t+1 / 2 a^{2}$
$\vartheta=\omega_{1} t+\frac{1}{2} \alpha t^{2}$
Speed $=\quad \frac{\text { Distance }}{\text { Time }}$
Acceleration =
Velocity Time
$\mathrm{s}=\mathrm{r} \vartheta$
$\mathrm{V}=\omega \mathrm{r}$
$a=\alpha r$

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## Torque and Angular

$T=I \alpha$
$I=m k^{2}$
$P=T \omega$

## Energy and Momentum

Potential Energy $=\mathrm{mgh}$
Kinetic Energy
Linear $=1 / 2 \mathrm{mv}^{2}$
Angular $=1 / 2 l \omega^{2}$
Momentum
Linear $=m v$
Angular $=1 \omega$
Vibrations
Linear Stiffness $k=\frac{F}{\delta}$
Circular frequency $\omega_{n}=\sqrt{\frac{k}{m}}$
Frequency $f_{n}=\frac{\omega_{n}}{2 \pi}=\frac{1}{T_{n}}$
$x=r \cos \omega t$
$v=-\omega \sqrt{r^{2}-x^{2}}=-\omega r \sin \omega t$
$a=-\omega^{2} x$
$f=\frac{1}{T}$
$T=\frac{2 \pi}{\omega}$
$F=m a$

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## Numerical Methods



In both approximation rules:

$$
h=\frac{b-a}{n} \quad \text { where } n \text { is the number of strips. }
$$

Trapezium Rule for $\boldsymbol{n}$ Strips:

$$
\int_{a}^{b} f(x) d x \approx \frac{1}{2} h\left[y_{0}+2\left(y_{1}+y_{2}+y_{3}+\cdots \cdots+y_{n-1}\right)+y_{n}\right]
$$

Simpson's Rule for $\boldsymbol{n}$ Strips (where $\boldsymbol{n}$ must be even):

$$
\int_{a}^{b} f(x) d x \approx \frac{1}{3} h[y_{0}+4(\overbrace{\left(y_{1}+y_{3}+\cdots+y_{n-1}\right.}^{\text {Odd numbered terms }})+2(\underbrace{y_{2}+y_{4}+\cdots+y_{n-2}}_{\text {Even numbered terms }})+y_{n}]
$$

## Newton-Raphson Method

Approximate solutions to $f(x)=0$ (i.e. roots of the function $f$ ) can be found using the iterative scheme:

$$
x_{n}=x_{n-1}-\frac{f\left(x_{n-1}\right)}{f^{\prime}\left(x_{n-1}\right)}
$$

with $x=x_{0}$ some (given) initial point.

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## Integration and Differentiation

## Differentiation from First Principles

The first derivative of a function $f(x)$ with respect to $x$ is given by:

$$
f^{\prime}(x)=\lim _{h \rightarrow 0}\left(\frac{f(x+h)-f(x)}{h}\right) .
$$

Table of Derivatives and Integrals
In the table below, $m, n$ are any real numbers.

| $\int F(x) d x$ | $F(x)$ | $F^{\prime}(x)$ |
| :---: | :---: | :---: |
| $\int f(x) d x+\int g(x) d x$ | $f(x)+g(x)$ | $f^{\prime}(x)+g^{\prime}(x)$ |
| $m \int f(x) d x$ | $m f(x)$ | $m f^{\prime}(x)$ |
| $m x+C$ | $m$ | 0 |
| $\frac{x^{n+1}}{n+1}+C \quad(n \neq 1)$ | $x^{n}$ | $n x^{n-1}$ |
| $\ln (x)+C$ | $\frac{1}{x}$ | $-\frac{1}{x^{2}}$ |
| $\frac{1}{m} e^{m x}+C$ | $e^{m x}$ | $m e^{m x}$ |
| $x-x \ln (m x)+C$ | $\ln (m x)$ | $\frac{1}{x}$ |
| $\frac{1}{m} \sin (m x)+C$ | $\cos (m x)$ | $-m \sin (m x)$ |
| $-\frac{1}{m} \cos (m x)+C$ | $\sin (m x)$ | $m \cos (m x)$ |

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## Rules of Differentiation

$$
\begin{aligned}
\text { PRODUCT RULE: } & \frac{d}{d x}(f(x) g(x))=f^{\prime}(x) g(x)+f(x) g^{\prime}(x) \\
\text { QUOTIENT RULE: } & \frac{d}{d x}\left(\frac{f(x)}{g(x)}\right)=\frac{f^{\prime}(x) g(x)-f(x) g^{\prime}(x)}{g(x)^{2}} \\
\text { CHAIN RULE: } & \frac{d}{d x}(f(g(x)))=g^{\prime}(x) \cdot f^{\prime}(g(x))
\end{aligned}
$$

## Rules of Integration

$$
\begin{aligned}
\text { INTEGRATION BY PARTS: } & \int_{x=a}^{b} f(x) g^{\prime}(x) d x=[f(x) g(x)]_{x=a}^{b}-\int_{x=a}^{b} f^{\prime}(x) g(x) d x \\
\text { INTEGRATION BY SUBSTITUTION: } & \int_{x=a}^{b} F(g(x)) g^{\prime}(x) d x=\int_{u=g(a)}^{g(b)} F(u) d u \\
& \text { with the substitution } u=g(x) \text { and where } F^{\prime}(x)=f(x) .
\end{aligned}
$$

## Local Maxima and Minima of a Function

A curve defined by $y=f(x)$ in terms of some function $f$ has stationary points where $f^{\prime}(x)=0$. These are then classified using the Second Derivative Test:

Let $x=a$ be a stationary point of $f(x)$ then:

$$
\begin{array}{lll}
f^{\prime \prime}(a)>0 & \Longrightarrow & x=a \text { is a local minimum } \\
f^{\prime \prime}(a)<0 & \Longrightarrow & x=a \text { is a local maximum } \\
f^{\prime \prime}(a)=0 & \Longrightarrow & \text { the test is inconclusive. }
\end{array}
$$

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## Differential Equations

## First-order ODEs:

The following denote methods of solving first-order ordinary differential equations:
DIRECT INTEGRATION

$$
y^{\prime}=f(x) \quad \Longrightarrow \quad y=\int f(x) d x
$$

SEPARATION OF VARIABLES

$$
y^{\prime}=f(x) \cdot g(y) \quad \Longrightarrow \quad F(y)=\int f(x) d x \quad \text { where } \quad F^{\prime}(y)=\frac{y^{\prime}}{g(y)}
$$

INTEGRATING FACTOR

$$
y^{\prime}+f(x) y=g(x) \quad \Longrightarrow \quad y=\frac{1}{M(x)} \int M(x) g(x) d x
$$

where $M(x)=\exp \left(\int f(x) d x\right)$ is the integrating factor.

## Second-order ODEs

The solution to the second-order homogeneous differential equation with constant coefficients:

$$
y^{\prime \prime}+A y^{\prime}+B=0
$$

is determined by the roots of its auxiliary equation:

| Case | Roots | General Solution |
| :---: | :---: | :---: |
| I | Two real: $M_{1}, M_{2}$ | $y=A e^{M_{1} x}+B e^{M_{2} x}$ |
| II | One real (double) root: $M$ | $y=(A+B x) e^{M x}$ |
| III | Complex conjugate pair: $P \pm i \omega$ | $y=(A \cos (\omega x)+B \sin (\omega x)) e^{P x}$ |

## END OF FORMULA SHEETS

